APPENDIX 1

```
void sw ( )
(

#define iw = 12;                                          /* instruction
                                                          width */

#define mw = 3:                                           /* memory width */
#define CONST = 0                                         /* push constant */
#define LOAD = 1                                          /* push variable */
#define GLOBAL = 2                                        /* push address */
#define PUTCHAR, = 15 /*                                  put a character along the
                                                          standard output channel*/
#define GETCHAR = 16 /*                                   get a character from the
                                                          standard input channel */


...

rom program []
#include "prog.o" ): ram stack[1«mw] with dualport = 1 ];
ram memory[1«mw] unsigned iw PC, ir, tos;
unsigned mw sp;

do par it = program[pc]: PC = PC + 1;
tos = stack[sp-1];                                        /* save top of
                                                          stack to avoid
                                                          two ram accesses
                                                          in one cycle
                                                          */


switch (ir)
case
CONST par
        stack[sp] = program[pc];
        sP = sP+l:
        PC = Pc+l:
        ]
        break;
case LOAD
        stack[sp-1] = memory[tos<-mw];
        break;
case STOP break; default :                                /* unknown opcode */
while (1) delay;


] while (ir != STOP);
```

]

Register transfer level description of simple processor

5

APPENDIX 2

```
void main() { char hwswchan;
char unsigned 8 port:

       par {
              parallel_,,port(port);
              SyncGen():

                     initialiseRam(port);
                     par {
                            display(hwswchan): sw(hwswchan);
                            y 1 }
       }

       RTL description of main
```

APPENDIX 3

CALCULATION PROCESS

```
 5   /*
     * Channel communicating object positions
     */ chap unsigned 17 position;


     /*
10   * Channel communicating segment information
     */
     chanout unsigned 9 segment;


     /*
15   * Channel communicating button information
     */
     chanin unsigned 2 buttons;


     /*
20   * Overall par
     */ par

             /*
             * Mass motion
25           */

                 /*
                 * Positions of each mass, 9+8 fixed point
                  */
30               unsigned 17 p0, pl, p2, p3, p4, p5, p6, p7;
                 /*
                 * Velocity of each mass, 9+8 fixed point
                  */
                 int 17 vl, v2, v3, v4, v5, v6, v7; '
35               /*
                 * Accelerations of each mass, 9+8 fixed point
                  */
                 int 17 al, a2, a3, a4, a5, a6, a7;
                 /*
40               * Sutton status
                  */
                 unsigned 2 button status;
                 /*
                 * Initial setup of positions
45                */
```

```
p0 = 65536;
pl = 65536;
p2 = 65536;
p3 = 65536;
p4 = 65536;
p5 = 65536;
p6 = 65536
p7 =65536

/*
* Forever
*/
while (1)
    {

    /*
    * Send successive positions down position channel
    */
    send(position, p0);
    send(position, p1);
    send(position, pl);
    send(position, p2);
    send(position, p2);
    send(position, p3);
    send (position, p3);
    send(position, p4);
    send(position, p4);
    send(position, p5);
    send(position, p5);
    send(position, p6);
    send(position, p6);
    send(position, p7);

    /*
    * Update positions according to velocities
    */
    pl +_ (unsigned 17)vl;
    p2 +_ (unsigned 17)v2;
    p3 +_ (unsigned 17)v3;
    p4 +_ (unsigned 17)v4;
    p5 +_ (unsigned 17)v5;
    p6 +_ (unsigned 17)v6;
    p7 +_ (unsigned 17)v7;

    /*
```

5

10

15

20

25

30

35

40

45

```
                    * Update velocities according to accelerations
                    */
                   vl += al - (v1 » 6);
                   v2 += a2 - (v2 » 6) ;
     5             v3 += a3 - (v3 » 6);
                   v4 += a4 - (v4 » 6);
                   v5 += a5 - (v5' » 6);
                   v6 += a6 - (v6 » 6);
                   v7 += a7 - (v7 » 6);
    10
                   /*
                    * Set accelerations according to relative positions
                    */
                   al = (int 17)(((p2 » 8) - (pl » 8)) + ((p0 » 8) - (pl » 8)));
    15             a2 = (int 17)(((p3 » 8) - (p2 » 8)) + ((pl » 8) - (p2 » 8))):
                   a3 = (int 17)!!(p4 » 8) - (p3 » 8)) + ((p2 » 8) - !p3 » 8)));
                   a4 = (int 17)(((p5 » 8) - (p4 » 8)) + ((p3 » 8) - (p4 » e> >;
                   a5 = (int 17)((!p6 » 8) - (p5 » 8)) + ((p4 » 8) - (p5 » 8)));
                   a6 = (int 17)(((p7 » 8) - (p6 » 8)) + ((p5 » 8) - (p6 » e > ) ;
    20             a7 = (int 17)((p6 » 8) - (p7 » 8));

                   /*
                    * Get button information
                    */
    25             receive(buttons, button status);

                   /*
                    * Fix top point according to buttons
                    */ if (button status & 1)
    30
                       p0 = 65536 - 16384;
                       )
         else       if (button status & 2)
                       (
    35                   p0 = 65536 + 16384;

         else

                       p0 = 65536;
    40                 }
                   )
                   /*
                    * nine drawing
                    */
    45             (
                       /*
```

```
            * Positions of previous and next massess positions
            */
           unsigned 17 prev_.pos, next pos, curr pos;
           /*
  5         * Which line of interpolation
            */
           unsigned char line;
           /*
            * Forever
 10         */
           while (1)
              (
              /*
               * Receive previous mass position
 15            */
              receive (position, prev posy;
              curr pos = prev pos;
              /*
               * Read next mass position
 20            */
              receive(position, next posy;
              /*
               * Do 64 lines of interpolation
               */
 25           for (line = 0; line != 64; line++)
                 (
                  /*
                   * Send start position of segment
                   */
 30               send(segment, curr pos >> 8);    /**width adjustment:17 along
                                                    channel of width 9 so takes bottom 9
                                                    bits*/

                  /*
 35                * Move by appropriate amount (1/64  total change)
                   */
                  curr pos +_ (unsigned 17)(((int 17)next pos -
                                            (int 17)prev pos) >> 6);
                  /*
 40                * Send end position of segment
                   */
                  send(segment, curr pos >> 8):
                 )
              )
 45        )
           )
```

DISPLAY PROCESS

5

```
/* standard includes */
        #include "hammond.h"
    #include "syncgen.h"
    #include "stdlib.h"
```

10
```
    #include "parallel.h"


        /*
* Segment information channel */ chap segment;
```

15
```
        /*
* Button information channel */
chan buttons:


        /
```

20
```
* Include dash generated stuff */
#include "handelc.h"


        /*
* Main program */
```

25
```
void main() (
        /
* Scan positions
*/ unsigned sx, sy;
```

30
```
        /
* Vdeo output register
*/
unsigned 1 video;
```

35
```
        /*
* Video output bus
*/

interface bus out() video out(Visible(sx, sy) ?
```

40
```
(video ? (unsigned 12)Oxfff : 0) 0) with video spec;

#ifndef SIMULATE
        /*
* Left button input bus
```

45
```
*/
interface bus in (unsigned 1) button_left()
```

```
            with button white spec;

        /*
        * Right button input bus
 5      */
            interface bus in(unsigned 1) button right()
                with button_black spec;
        #endif

10      /*
        *
                Overall par
        */ par {
        /*
15          * VGA sync generator
            */
        SyncGen(sx, sy, hsync pin, vsync pin);
        /*
            *
20              Dash generated hardware
            */
        hardware();
        /*
            * Run-length decoder
25          */
        {
        /*
            * Segment start and end positions
            * /
30      unsigned start, end;
        /*
            * Forever
            */
        while (1)
35          {
            while (sy != 448)
                /*
                * Read segment information
                */
40          segment ? start;
            segment ? end;
            /*
                * Get in the right order
                */
45          if (start > end)
                {
```

```
                              par
                               {

        end = start;
 5      start = end;.
        )



                              /*
10      * Make at least 1 pixel visible
        */
        if (start == end)
                              end++;

15      /*
                         * Wait
        */
                         while (sx != 0)
                           delay;
20                       /*
                           * Draw a scanline worth
                           * /
                         while (sx != 512)
                             if ((sx <- 9) >= start && (sx <- 9) < end)
25
                                video = 1;
                              else
                             video = 0;

30                           )
                        /*
                          * Communicate button status
                          */
        #ifdef SIMULATE
35                       buttons ! 1;
        #else
                         buttons ! button left.in @ button right.in;
        #endif
                         /*
40                         * Wait
                            */
                         while (sy != 0)
                           delay;
                       )
45
```